

# Zero Turn Front Loader

Mechanical and Aerospace Engineering Advisor: John Liu Tanner Bowers, Trenton Mulnix, Jordan Winebrenner, Isaac Zager

### Abstract

Four MAE seniors designed and implemented a safe and functioning skid-steer style front loader on Joe Thompson's (Lab instructor) zeroturn mower. The product is designed to meet needs and requirements set by the customer.

The team focused solely on the design and simulation of the loader during the fall semester. A complete SolidWorks CAD model was developed. Each part was tested on ANSYS simulation software. The dynamics and statics of the loader were verified to meet requirements in MATLAB.

During the spring semester, the team cut, welded and assembled the front loader structure and implemented systems to make the front loader compatible with the mower. As problems occurred, the team would collaborate and iterate to reach the current prototype stage.

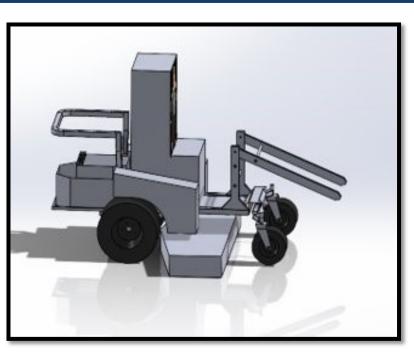
## Customer Needs and Requirements

- Transport mulch, sand, dirt and gravel
- User-friendly controls
- Easy to get on and off mower
- Must be painted/finished to match mower
- Water resistant
- Ability to dump into truck bed
- Easily detachable
- Do not overload max weight of mower

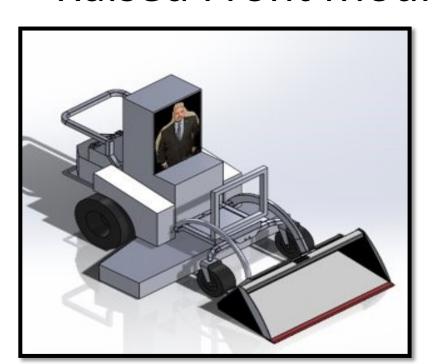


- Max step height of 12" to get on and off mower
- Lift and dump individually with 'skid steer' like controls
- Lift at least 500 lbs+ 240 lb bucket
- Minimum lift height of 50 inches
- Minimum dig height of 2" below grade
- Minimum speed of 0.5 ft/s during operation of arms/bucket
- Detachable within 30 minutes for one person
- Must be finished in orange or black to match mower
- Front Loader unit must not exceed mowers capacity of 1,500 lbs on Rear trans-axle

## Concept Selection

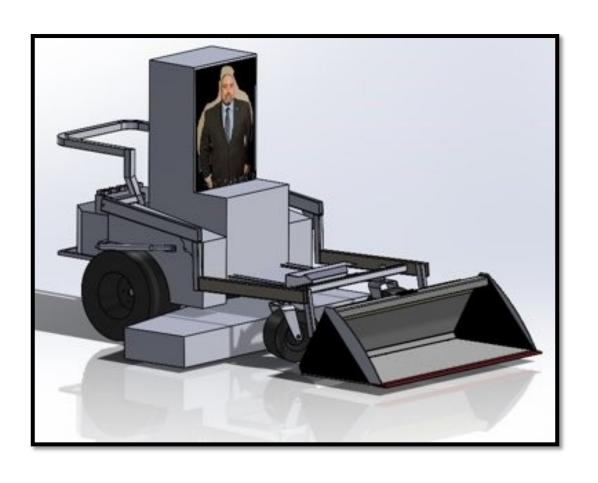


Raised Front Mount



Low Front Mount

### Raised Front Mount

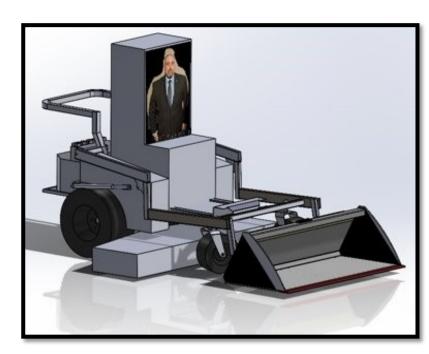


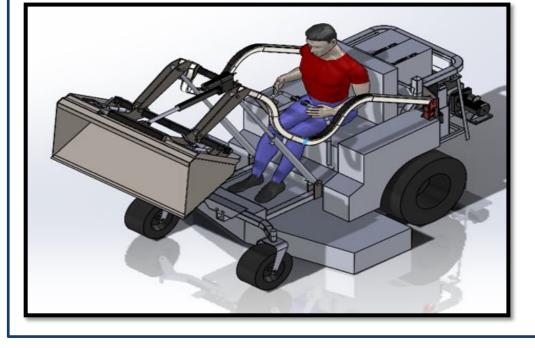
Skid Steer Mount

# Design Solution

#### First Iteration

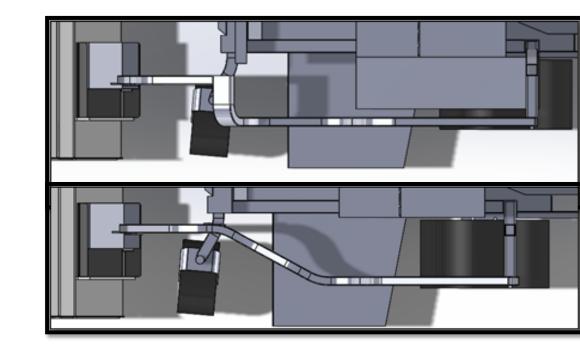
- Arms are welded together
- Stress points were not considered
- Mount at shoulders of ROPS





#### Second Iteration

- Arms bent inward to install quick attach
- Manufacturability not considered



#### Third Iteration

- Arms bent inward
- Plate added to end of arms
- Pivot point moved upward

#### **Caster Mount**



- Allows extra front load capacity
- Material ¼" A36 Mild Steel
- Two caster wheels with combined strength of 1,200 lbs

### **Pump Rack**

- Protect and install hydraulic pump
- Material 1/4" Angle iron and expanded metal



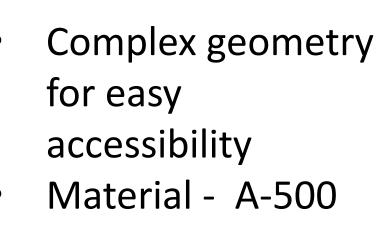
### Lap Bars



- Provide clearance Bender for lift arm
- Material 6061 aluminum piping

#### Arms

Manufacturing



- Mild Steel Bent using Hydraulic Tube
- movement

#### **Basket**



- Hold batteries
- Extra storage space
- Modified ROPS
- Material Expanded metal and ¼" Angle iron

### Final Assembly

- Complete functional loader
- Added weight 844 lbs
- Total 2,282 lbs

# Testing and Validation

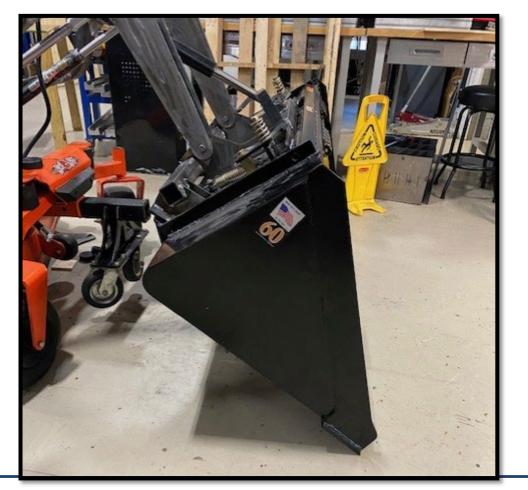
Test 1: Weight Requirement

Add ~500 lbs of mass to bucket and lift two feet to verify functionality Test 2: Height Requirement

- Lift arms at 50 inches and tilt bucket up and down
- Dig two inches below grade by tilting attached bucket

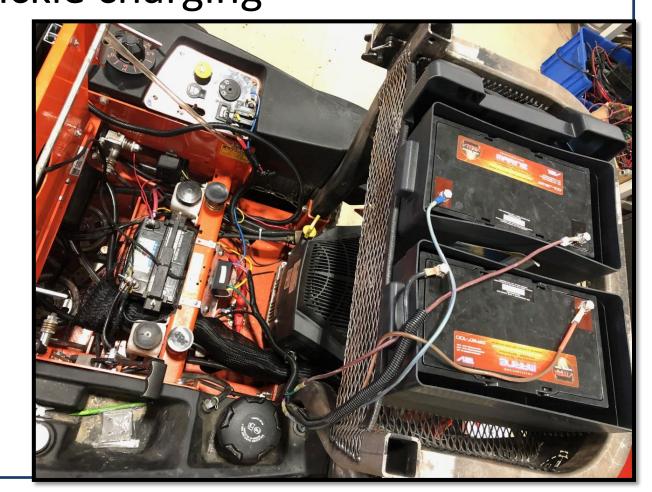
Test 3: Speed Requirement

- Under no load, extend attached cylinders fully
- Record full lift time for unloaded case



Test 4: Charge Testing

- Operate both electrical and hydraulic components
- Test combiner to verify batteries gain voltage by trickle charging



# Acknowledgments







Thank you, Dr. Liu, Joe Thompson II, and the Wade Department of

Mechanical and Aerospace Engineering for your contributions to this project

Thank you to our donors! SOS Hydraulics – Hydraulic Pump and labor Parker Hannifin – Hydraulic Cylinders Vestil Manufacturing – Steel tubing and plate

